

L Number	Hits	Search Text	DB	Time stamp
1	166	attitude and directional and turn and ((angular or rotation\$2) near5 rate) and compensat\$3	USPAT	2003/10/07 14:38
2	12573	gyro\$6	USPAT	2003/10/07 14:42
3	104	(attitude and directional and turn and ((angular or rotation\$2) near5 rate) and compensat\$3) and gyro\$6	USPAT	2003/10/07 14:58
4	25	( (proof adj4 mass) with suspen\$4) and piezo\$9 and electrode\$ and substrate\$ and chip\$	USPAT	2003/10/07 15:01

L Number	Hits	Search Text	DB	Time stamp
1	6704	ddd	USPAT	2003/10/07 12:43
2	370	gyro\$7 and piezo\$9 and ((rotation\$2 or angular) near5 rate) and compensat\$3	USPAT	2003/10/07 12:45
3	145	gyro\$7 and (piezo\$9 same ((rotation\$2 or angular) near5 rate)) and compensat\$3	USPAT	2003/10/07 12:45

L Number	Hits	Search Text	DB	Time stamp
1	522	gyro\$6 and piezo\$9 and (rotation\$2 with rate)	USPAT	2003/10/07 10:59
2	82	gyro\$6 same piezo\$9 same (rotation\$2 with rate)	USPAT	2003/10/07 11:05